

Directional control valves, pilot-operated, with electrical position feedback and integrated electronics (OBE)

# Type 4WRTE



### **RE 29083**

Edition: 2017-03 Replaces: 08.13

- ▶ Size 10 ... 35
- Component series 4X
- Maximum operating pressure 350 bar
- ► Rated flow 25 ... 1000 I/min

#### **Features**

- ► Reliable proven and robust design
- ▶ Safe
  - Automatic pressure compensation in the control chambers of the main stage by the pilot control valve
  - Control spool of the main stage in the springcentered central position and/or in the offset position
  - Optionally with spool position monitoring
- ► Flexible suitable for position, speed and pressure control
- Precise high response sensitivity and little hysteresis

# **Contents**

Features	1
Ordering code	2, 3
Symbols	3, 4
Function, section	5, 6
Pilot oil supply	7, 8
Technical data	8 10
Electrical connections and assignment	10
Block diagram	11
Characteristic curves	12 18
Dimensions	19 26
Inductive position switch	27
Accessories	28
Project planning, installation and commissioning	29
Further information	29

# **Ordering code**

01	02	03	04	05	06	07	08		09		10	11	12	13		14	15	16	17	
4	WRT	Е						-	4X	/	6E	G24		K31	/				*	
	· · · · · ·								•					•	•					
01	4 main p	orts																	4	
02	Direction	nal coi	ntrol v	alve, p	oilot-o	perate	ed												WRT	r
03	With inte	egrate	d elec	tronic	:S														E	
04	Without	spool	l posit	ion m	onitori	ing													no coo	de
	With spo						3 NG	35 o	nly)										М	
05	Size 10																		10	
	Size 16																		16	
	Size 25																		25	
	Size 27																		27	
	Size 32																		32	
	Size 35																		35	
06	Symbols		F F1	M/C	-t	الطنوو				2										
06						OSSIDIE	e versi	on se	e page	3										
Rate 07	d flow (Δρ – Size 10		ar/co	ntrol e	edge)															
"	25 l/min		hol F	W6- \	N8- an	d V or	1\/ \\/i+1	h flov	/ chara	rteri	stic "I "	)							25	
	50 l/min											)							50	
	90 I/min		DOILI	, , ,	anu v	1 Offing	VVILII	IIOW C	iiai acto	511311	C L)								100	
	- Size 10																		100	
	150 l/mi		nhal \/	1 only	, with t	flover of	haraat	orieti	o "I ")										150	
			IDOI V	1 Offiny	VVILII	ilow Ci	iiai act	eristic	J L )											
	220 l/mi - Size 2!																	 	220	
																			220	
	220 l/mi																		350	
	350 l/mi																		350	
																			F00	
	500 l/mi																		500	
	400 l/mi																		400	
	<u> </u>																		400 600	
	600 I/mi																		600	
	1000 l/m																		1000	
																			1000	
Flow 08	<b>characte</b>	ristic																		
00	Linear w	ith fin	e conf	trol ra	nge														L P	
09	Compon					// 0.	uncha	nged	installa	tion	and m	ounting	dime	neione)					4X	
			.1165 4	4	J (40 .	431	uncnd	iigeu	motalla	iciOII	and III	Juliulig	unne	1310113)					1 41	
10	Proporti		olenoi	id with	n deta	chable	coil (	NG6)											6E	
11	Direct vo																		G24	
		nuge	∠-† V																G24	-
12	oil flow External	nilot :	oil sur	ndy c	vterna	l nila+	oil ret	ture											no coo	de .
12	Internal																			ие
	External																		E T	
	Internal																			
_				hià' iu	remal	μιιστ (	on rett	41 (I											ET	
	rical conr			nocto	r. 000	200to=	DIN F	NI 175	201 00	1/1									K31 <sup>1</sup>	1)
13	Without	ıııdlıl	ig con	песто	i, conf	iector	אווע ב	IN 1/5	)Z01-8(	/4									K31 -	

# **Ordering code**

1	WRT							AV	 6E	G24		1/24				*
01	02	03	04	05	06	07	80	09	10	11	12	13	14	15	16	17

#### Interfaces of the control electronics

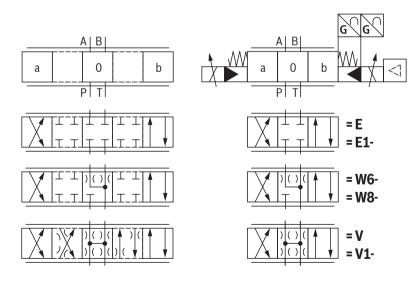
1	L4	Command value/actual value ± 10 V	A1
		Command value/actual value 4 20 mA	F1
		Command value/actual value ± 10 V, enable signal (pin C)	<b>A5</b> <sup>2)</sup>

#### Seal material

ocu.	muteriui .	
15	NBR seals	М
	FKM seals	V
	Observe compatibility of seals with hydraulic fluid used.	
16	Without electronics protection membrane	no code
	With electronics protection membrane	-967
	•	
17	Further details in the plain text	*

- Mating connectors, separate order, see page 28 and data sheet 08006.
- When replacing the component series 3X by component series 4X, the electronics interface is to be defined with A5 (enable signal at pin C).

# **Symbols**



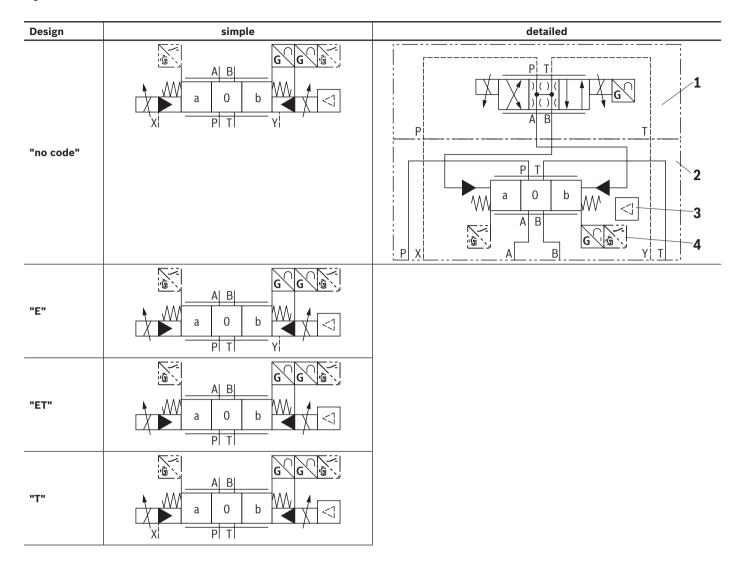
With symbol E1-, V1- and W8-:

 $P \rightarrow A: \boldsymbol{q}_{V \text{ max}}$   $B \rightarrow T: \boldsymbol{q}_{V}/2$  $P \rightarrow B: \boldsymbol{q}_{V}/2$   $A \rightarrow T: \boldsymbol{q}_{V \text{ max}}$ 

### Motices:

► Representation according to DIN ISO 1219-1. Hydraulic interim positions are shown by dashes.

# **Symbols**



- 1 Pilot control valve
- 2 Main valve
- 3 Integrated electronics (OBE)
- 4 Design with spool position monitoring "M"

Motice:

Representation according to DIN ISO 1219-1.

#### **Function**, section

Valves of type 4WRTE are pilot-operated directional control valves with electrical position feedback, integrated electronics (OBE) and optional spool position monitoring.

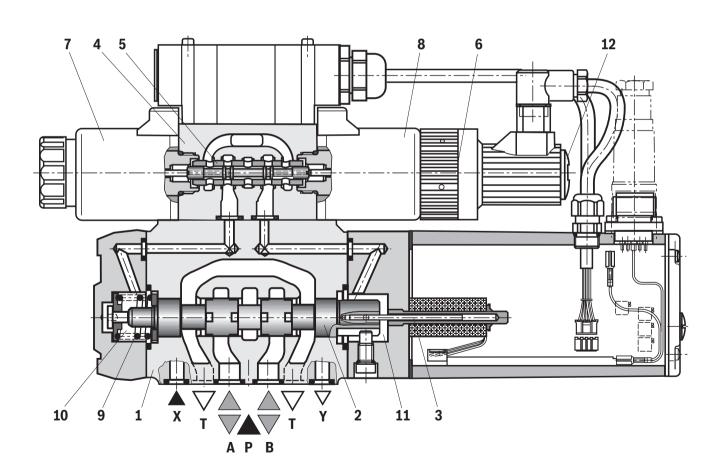
#### Set-up

The valve basically consists of 3 main assemblies:

- ► Housing (1) with main stage control spool (2) and optional spool position monitoring (13)
- ► Integrated electronics (optionally with electronics protection membrane (14)) with inductive position transducer (3) of the main stage
- ▶ Pilot control valve (4) with control spool/socket unit (5), inductive position transducer (6) and pressure feed back for central position of the main stage control spool (2)

#### **Function**

- ▶ With de-energized proportional solenoids (7; 8) central position of the main stage control spool (2) due to centering spring (9) and pressure feed back
- ► Control of the main stage control spool (2) via the pilot control valve (4) → the main stage control spool (2) is positioned in a regulated manner
- ► Controlling the control spool of the pilot control valve (4) by changing the solenoid force of the proportional solenoids (7; 8)
- ► Connection of the command and actual values in the integrated electronics
- ► Pilot oil supply to the pilot control valve internally via port P or externally via port X Pilot oil return internally via port T or externally via Y to the tank
- ▶ With a command value of 0 V, the electronics control the main stage control spool (2) in central position



#### Function, section

#### Spool position monitoring

The spool positions of the main stage control spool (2) are detected by the inductive position switch (13) and displayed via two switching outputs with a preset logic. If the fixedly set switching points are exceeded, the deviation from the zero position is monitored within the control spool overlap (see page 27).

The switching signals can be used in a superior control for monitoring functions. The electrical connection is implemented separately via a 4-pole connector M12x1 with two pins for signal output and two pins for voltage supply.

#### Area of application

The valve can be used in safety-related two-channel applications (category 3, PL d and category 4, PL e according to EN 13849-1) as switch-off element for one channel. The valve meets the requirements of a secure start inhibitor according to EN 60204, stop category 0. If safety requirements are needed, the supply voltage of the valve must be safely disconnected based on the required safety level (category PL).

Depending on the application and the requirements of work equipment-specific standards according to EN 13849-1, the user must provide appropriate monitoring/plausibility checks which comply with the required diagnostic coverage DCavg using a superior control.

#### Electronics protection membrane "-967"

To prevent condensate formation in the housing of the integrated electronics (OBE), an electronics protection membrane (14) can be used.

Recommended for use outside industry-standard conditions with high ambient air humidity and significant cyclic temperature changes (e. g. outdoors).

#### Failure of supply voltage

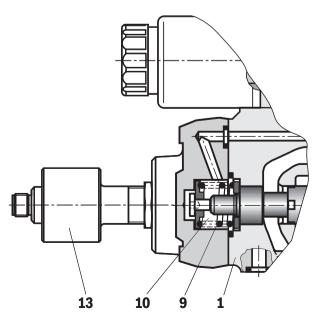
- ► Integrated electronics de-energize the solenoid in case of supply voltage failure or cable break
- ► Automatic pressure control on the same level in the control chambers (10 and 11) by the pilot control valve
- ► In case of pressure supply failure, centering of the main stage control spool by centering spring (9)
- ► Central position of the main stage control spool (2)

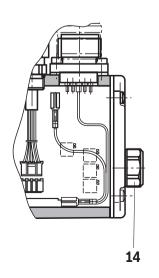
#### Notices:

► Failure of the supply voltage will lead to an abrupt standstill of the control axis. The acceleration forces occurring in this connection may cause machine damage.

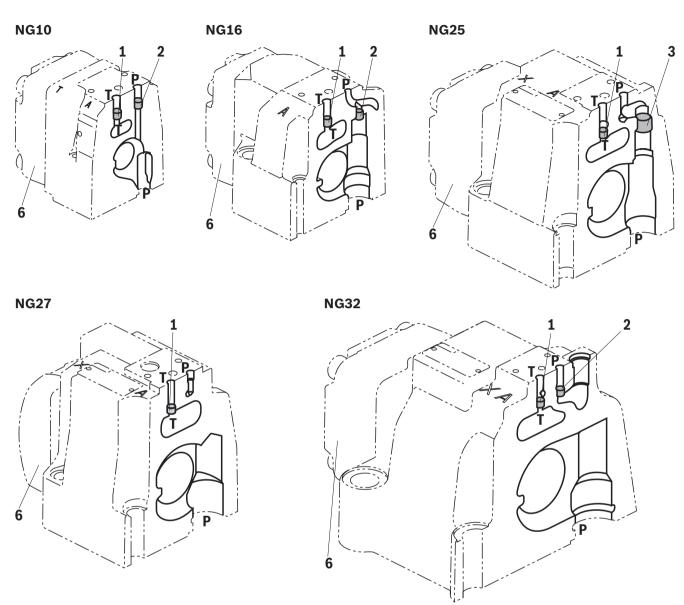
With control spool symbols E, E1-, W6- and W8-, the centering spring (9) sets the main stage control spool (2) in central position, control spools V- and V1 are switched to the preferred direction P to B and A to T in a tolerance range of 1% to a maximum of 11% of the control spool stroke.

- ► The PG fitting (12) must not be opened. Mechanical adjustment of the adjustment nut located below is prohibited and damages the valve.
- ► The zero point has been adjusted at the factory. Changes in the zero point may result in damage to the system and may only be implemented by instructed specialists.
- ► If the pilot control valve or the electronics are exchanged, the zero point has to be adjusted once again by instructed specialists.

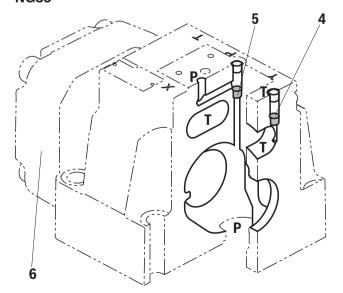




# Pilot oil supply (schematic illustration)







- Plug screw M6 according to DIN 906, wrench size 3pilot oil return
- 2 Plug screw M6 according to DIN 906, wrench size 3 pilot oil supply
- 3 Plug screw M12 x 1.5 according DIN 906, wrench size 6 pilot oil supply
- 4 Plug screw M10 x 1 according to DIN 906, wrench size 5 pilot oil return
- Plug screw M10 x 1 according DIN 906, wrench size 5pilot oil supply
- 6 Main stage housing cover (opposite the OBE)

Pilot oi	supply	Pilot oil return				
external	internal	external	internal			
2, 3, 5	2, 3, 5	1, 4	1, 4			
closed	open	closed	open			

Further explanations on page 8.

# Pilot oil supply

# "No code" version External pilot oil supply External pilot oil return

In this version, the pilot oil is supplied from a separate control circuit (external).

The pilot oil return is not directed into channel T of the main valve, but is separately directed to the tank via port Y (external).

# Version "E" Internal pilot oil supply External pilot oil return

With this version, the pilot oil is supplied from channel P of the main valve (internally).

The pilot oil return is not directed into channel T of the main valve, but is separately directed to the tank via port Y (external).

In the subplate, port X is to be closed.

# Version "ET" Internal pilot oil supply Internal pilot oil return

With this version, the pilot oil is supplied from channel P of the main valve (internally).

The pilot oil is directly returned to channel T of the main valve (internally).

In the subplate, ports X and Y are to be closed.

# Version "T" External pilot oil supply Internal pilot oil return

In this version, the pilot oil is supplied from a separate control circuit (external).

The pilot oil is directly returned to channel T of the main valve (internally).

In the subplate, port Y is to be closed.

#### **Technical data**

(For applications outside these parameters, please consult us!)

general			·			·	·	
Sizes	NG	10	16	25	27	32	35	
Weight	kg	8.7	11.2	16.8	17	31.5	34	
Installation position and commissioning information	Preferably	horizontal,	see data s	heet 07700				
Ambient temperature range	-20 +50	)						
Maximum storage time  Years 1 (if the storage conditions are observed instructions 07600-B)					bserved; re	efer to the o	perating	
MTTF <sub>D</sub> values according to EN ISO 13849	Years	150 <sup>1)</sup> (for more information see data sheet 08012)						
Sine test according to DIN EN 60068-2-6		10 2000 Hz / maximum of 10 g / 10 cycles / 3 axes						
Noise test according to DIN EN 60068-2-64		20 2000 Hz / 10 g <sub>RMS</sub> / 30 g peak / 30 min. / 3 axes						
Transport shock according to DIN EN 60068-2-27		15 g / 11 ms / 3 shocks / 3 axes						
Damp heat, cyclic, according to DIN EN 60068-2-30		Variant 2 +25 °C 24 hours	+55 °C, 90%	% 97% re	lative humi	dity, 2 cycle	s of	

With symbol E, E1, W6 and W8: in longitudinal control spool direction, there is sufficient positive overlap without shock/ vibration load; observe the installation orientation with regard to the main direction of acceleration.

# **Technical data**

(For applications outside these parameters, please consult us!)

hydraulic										
Sizes			NG	10	16	25	27	32	35	
Maximum	► Pilot control valve	Pilot oil supply <sup>2)</sup>	bar	25 315						
operating pressure	► Main valve	Port P, A, B	bar	350	350	350	270	350	350	
Maximum return	► Port T	Internal pilot oil return	bar	Static < 10						
flow pressure		External pilot oil return	bar	315	250	250	210	250	250	
	► Port Y		bar	Static < 10	)					
Rated flow $q_{Vnom}$			l/min	25	150	_	_	_	_	
with $\Delta p = 5 \text{ bar/c}$	ontrol edge			50	_	220	_	400	_	
				100	220	350	500	600	1000	
Maximum flow (re	ecommended)		l/min	170	460	870	1000	1600	3000	
	ort X or Y with steppe 0 to 100% (315 bar)	ed	l/min	7	14	20	20	27	29	
Pilot oil volume 0	100%		cm³	1.1	2.9	6.8	6.8	17.7	33.9	
Hydraulic fluid				See table below						
Hydraulic fluid te (at the valve work			°C	-20 +80	; preferabl	y +40 +80	)			
Viscosity range			mm²/s	20 380; preferably 30 45						
	ible degree of contam according to ISO 440	nination of the hydraulic flo 6 (c)	uid,	Class 18/16/13 <sup>4)</sup>						
Hysteresis			%	≤ 0.1						
Response sensitiv	vity		%	≤ 0.05						
Zero point calibra	ation (ex works) 5)		%	≤ 1						
Temperature drift	İ	(	%/10 °C	Zero shift	< 0.3					

Hydraulic fluid		Classification	Suitable sealing materials	Standards	Data sheet
Mineral oils	'	HL, HLP, HLPD, HVLP, HVLPD	NBR, FKM	DIN 51524	90220
Bio-degradable	► Insoluble in water	HETG	NBR, FKM	ISO 15380	90221
		HEES	FKM		
	► Soluble in water	HEPG	FKM	ISO 15380	
Flame-resistant	► Water-free	HFDU, HFDR	FKM	ISO 12922	90222
	► Containing water	HFC (Fuchs Hydrotherm 46M, Petrofer Ultra Safe 620)	NBR	ISO 12922	90223

#### Important information on hydraulic fluids:

- ► For further information and data on the use of other hydraulic fluids, please refer to the data sheets above or contact us!
- ► There may be limitations regarding the technical valve data (temperature, pressure range, life cycle, maintenance intervals, etc.)!
- ► The ignition temperature of the hydraulic fluid used must be 40 K higher than the maximum solenoid surface temperature.

#### ► Flame-resistant - containing water:

- Maximum operating pressure 210 bar
- Maximum pressure differential per control edge 175 bar
- Pressure pre-loading at the tank port >20% of the pressure differential, otherwise increased cavitation erosion
- Life cycle as compared to operation with mineral oil HL, HLP 50 ... 100%
- Maximum hydraulic fluid temperature 50 °C

<sup>3)</sup> Flow for deviating  $\Delta p$  (valve pressure differential):

$$q_x = q_{V \text{ nom}} \times \sqrt{\frac{\Delta p_x}{5}}$$

- 4) The cleanliness classes specified for the components must be adhered to in hydraulic systems. Effective filtration prevents faults and simultaneously increases the life cycle of the components.
  - For the selection of the filters see www.boschrexroth.com/filter
- 5) Related to the pressure-signal characteristic curve (symbol V)



Technical data (hydraulic) measured with HLP46,  $\vartheta_{\text{Oil}}$  = 40 °C ±5 °C

<sup>&</sup>lt;sup>2)</sup> For perfect system behavior, we recommend an external pilot oil supply for pressures above 210 bar.

# **Technical data**

(For applications outside these parameters, please consult us!)

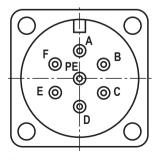
electrical, integrated ele	ctronics (OBE)						
Relative duty cycle		%	100 (continuous operation)				
Protection class accordin	g to EN 60529		IP 65 with mounted and locked plug-in connectors				
Supply voltage	► Nominal voltage	VDC	24				
	► Lower limit value	VDC	18				
	► Upper limit value	VDC	35				
Maximum admissible residual ripple Vpp			2.5 (Comply with absolute supply voltage limit value)				
Current consumption	► Maximum	А	1.6				
	► Impulse current	А	2.7				
Maximum power consum	ption	VA	72 (average 24)				
Required fuse protection,	external	A <sub>T</sub>	4 (time-lag)				
Voltage input "A1"	► Measurement range	VDC	-10 +10				
(differential input)	► Input resistance	kΩ	100				
Current input "F1"	► Input current	mA	4 (12) 20				
	► Input resistance	Ω	100				
Enable input "A5"	► Low level	VDC	0 2				
	► High level	VDC	11 <b>U</b> B				
Maximum coil temperatur	re <sup>6)</sup>	°C	150				

<sup>6)</sup> Due to the temperatures occurring at the surfaces of the solenoid coils, the European standards ISO 13732-1 and EN ISO 4413 need to be adhered to.

# **Electrical connections and assignment**

# **Connector pin assignment**

Pin	Signal	Interface A1	Interface F1	Interface A5					
Α	Supply valtage		24 V DC						
В	- Supply voltage	0 V							
С	Reference potential (actual value)/enable signal	Reference potential for	Enable signal 11 <b>U</b> B V DC						
D	Differential emplifies innect	±10 V	4 20 mA	±10 V					
Е	Differential amplifier input (command value)	0 V reference po	0 V reference potential for pin D and F						
F	Measuring output (actual value)	±10 V	4 20 mA	±10 V					
PE		Functional ground (directly connected to the valve housing)							

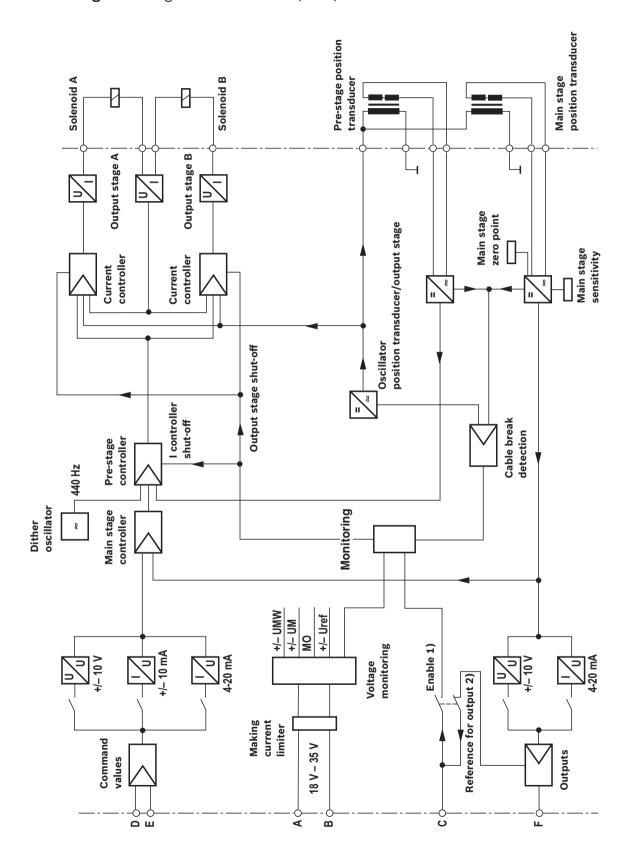


Command value:	▶ Reference potential at E and positive command value at D result in flow from $P \rightarrow A$ and $B \rightarrow T$ .
	▶ Reference potential at E and negative command value at D result in flow from $P \rightarrow B$ and $A \rightarrow T$ .
Connection cable	▶ Up to 25 m cable length type LiYCY 7 x 0.75 mm²
(recommendation):	▶ Up to 50 m cable length type LiYCY 7 x 1.0 mm²
	► Connect shield on PE only on the supply side

# Notices:

- ► Electrical signals provided via valve electronics (e.g. actual value) must not be used to switch off safety-relevant machine functions.
- ► Mating connectors, separate order, see page 28 and data sheet 08006.

# **Block diagram:** Integrated electronics (OBE)

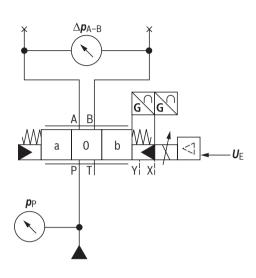


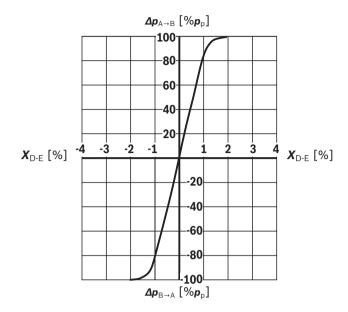
- 1) Only with electronics interface "A5"
- 2) Only with electronics interfaces "A1" and "F1"

# **Characteristic curves**

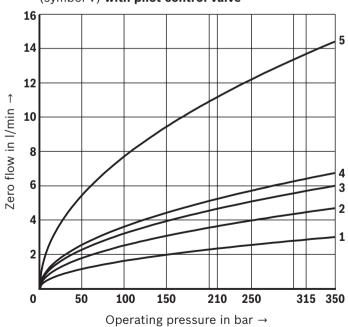
(measured with HLP46,  $\vartheta_{oil}$  = 40 °C ±5 °C and p = 100 bar)

# **Pressure amplification**

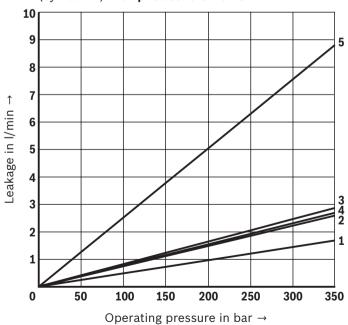




# Maximum zero flow of the main stage (symbol V) with pilot control valve



# Maximum internal leakage of the main stage (symbol W) with pilot control valve



**1** Size 10

**4** Size 32

**2** Size 16

**5** Size 35

**3** Sizes 25, 27

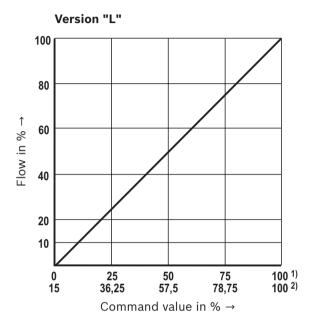
# **Characteristic curves**

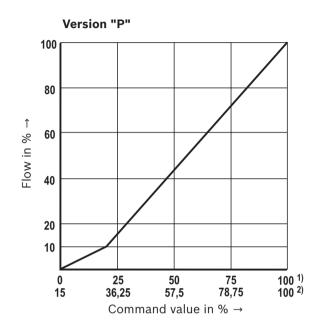
(measured with HLP46,  $\theta_{oil}$  = 40 °C ±5 °C)

### Flow command value function

 $(\Delta p = 5 \text{ bar/control edge})$ 

# Symbol E, W, and V



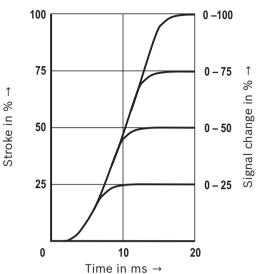


- 1) Positive overlap 0 ... 0.5% at symbol V
- $^{2)}$  Positive overlap 15% at symbol E and W

# Characteristic curves: Size 10

(measured with HLP46, 90il = 40 ±5 °C)

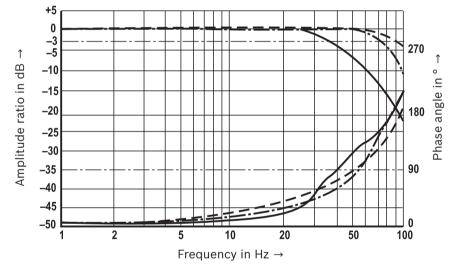
# Transition function with stepped electric input signals



#### Measured with:

- ▶ Pilot control valve: Port X = 100 bar
- ► Main stage: Port P = 10 bar

# Frequency response characteristic curves



# Measured with:

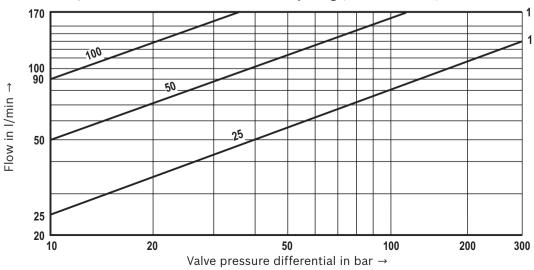
- ▶ Pilot control valve: Port X = 100 bar
- ► Main stage: Port P = 10 bar

\_\_\_\_\_ Signal ±100%

—--- Signal ±25%

— — — Signal ±5%

#### Flow/load function with maximum valve opening (tolerance ±10%)



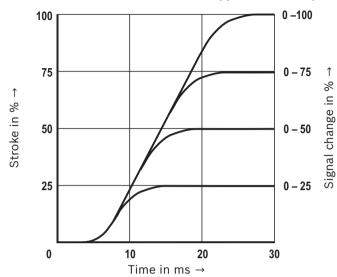
 Recommended flow limitation (flow velocity 30 m/s)

Bosch Rexroth AG, RE 29083, edition: 2017-03

# Characteristic curves: Size 16

(measured with HLP46,  $\vartheta_{oil} = 40 \pm 5$  °C)

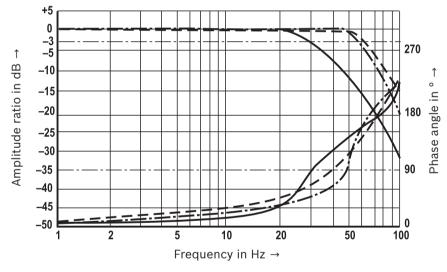
# Transition function with stepped electric input signals



#### Measured with:

- ▶ Pilot control valve: Port X = 100 bar
- ► Main stage: Port P = 10 bar

# Frequency response characteristic curves



#### Measured with:

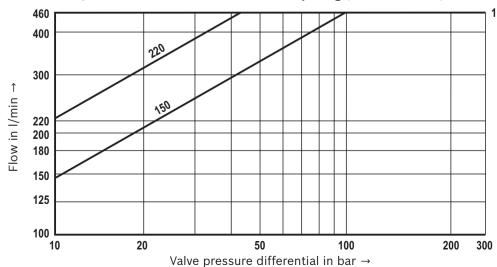
- ▶ Pilot control valve: Port X = 100 bar
- ► Main stage: Port P = 10 bar

Signal ±100%

—--- Signal ±25%

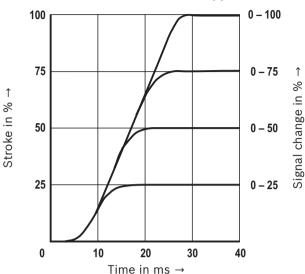
— — - Signal ±5%

### Flow/load function with maximum valve opening (tolerance ±10%)



 Recommended flow limitation (flow velocity 30 m/s) **Characteristic curves:** Size 25 and 27 (measured with HLP46,  $\vartheta_{oil}$  = 40 ±5 °C)

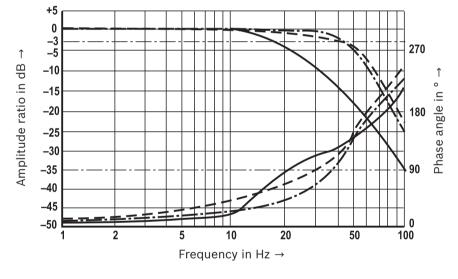
#### Transition function with stepped electric input signals



#### Measured with:

- ▶ Pilot control valve: Port X = 100 bar
- ► Main stage: Port P = 10 bar

# Frequency response characteristic curves



#### Measured with:

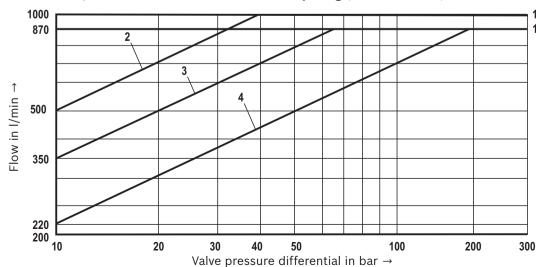
- ▶ Pilot control valve: Port X = 100 bar
- ► Main stage: Port P = 10 bar

\_\_\_\_\_ Signal ±100%

—--- Signal ±25%

— — — Signal ±5%

#### Flow/load function with maximum valve opening (tolerance ±10%)



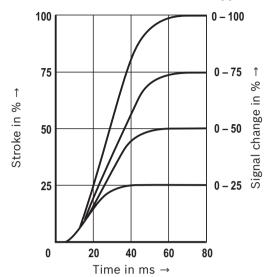
- Recommended flow limitation (flow velocity 30 m/s)
- **2** 500 NG27
- **3** 350 NG25
- **4** 220 NG25

Bosch Rexroth AG, RE 29083, edition: 2017-03

# Characteristic curves: Size 32

(measured with HLP46,  $\vartheta_{oil}$  = 40 ±5 °C)

### Transition function with stepped electric input signals

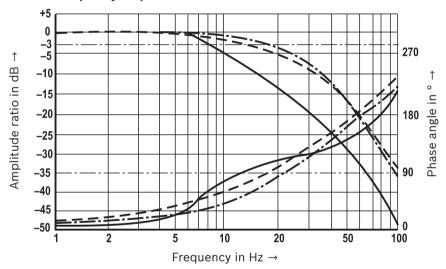


#### Measured with:

▶ Pilot control valve: Port X = 100 bar

► Main stage: Port P = 10 bar

#### Frequency response characteristic curves



#### Measured with:

▶ Pilot control valve: Port X = 100 bar

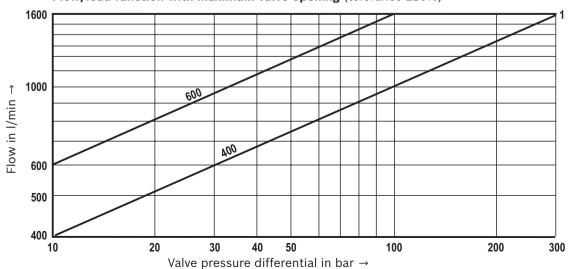
► Main stage: Port P = 10 bar

Signal ±100%

---- Signal ±25%

— — — Signal ±5%

#### Flow/load function with maximum valve opening (tolerance ±10%)

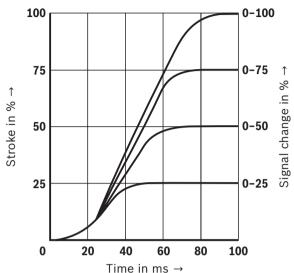


 Recommended flow limitation (flow velocity 30 m/s)

# Characteristic curves: Size 35

(measured with HLP46, 90il = 40 ±5 °C)

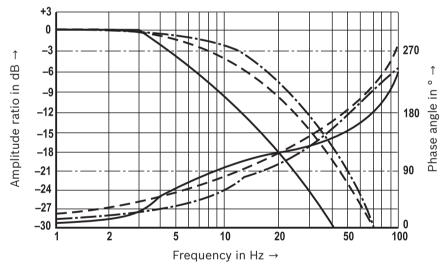
### Transition function with stepped electric input signals



#### Measured with:

- ▶ Pilot control valve: Port X = 100 bar
- ► Main stage: Port P = 10 bar

### Frequency response characteristic curves



#### Measured with:

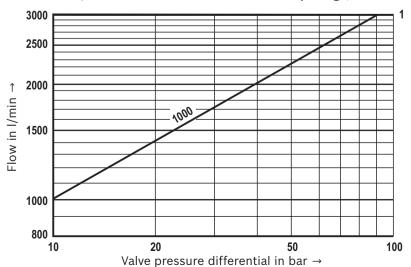
- ▶ Pilot control valve: Port X = 100 bar
- ► Main stage: Port P = 10 bar

Signal ±100%

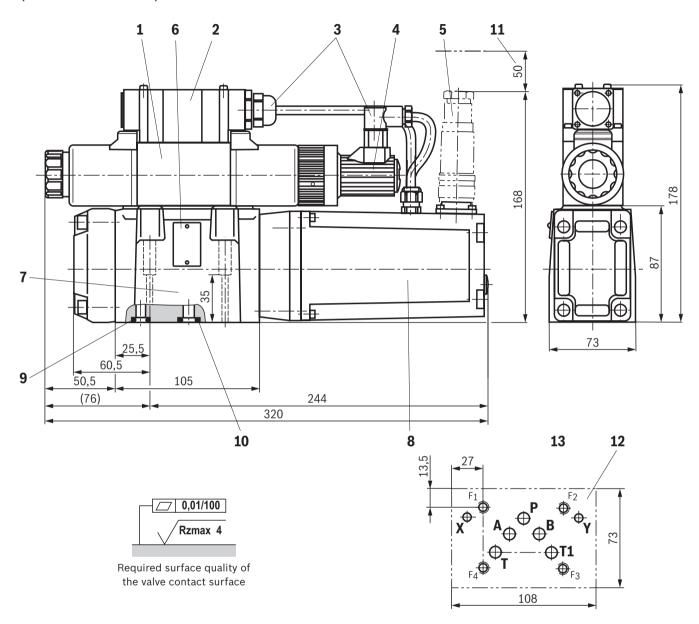
—--- Signal ±25%

— — — Signal ±5%

#### Flow/load function with maximum valve opening (tolerance ±10%)



 Recommended flow limitation (flow velocity 30 m/s) **Dimensions:** Size 10 (dimensions in mm)



- 1 Pilot control valve
- 2 Electrical connection
- 3 Wiring and mating connector
- 4 Inductive position transducer (pilot control valve)
- 5 Mating connector 6-pole + PE (separate order, see page 28 and data sheet 08006)
- 6 Name plate
- 7 Main valve
- 8 Integrated electronics (OBE) and inductive position transducer (main valve)
- 9 Identical seal rings for ports X, Y
- 10 Identical seal rings for ports A, B, P, T, T1
- **11** Space required for connection cable and to remove the mating connector
- **12** Machined valve contact surface, porting pattern according to ISO 4401-05-05-0-05 (ports X, Y as required)

**Subplates** (separate order) with porting pattern according to ISO 4401-05-05-0-05 see data sheet 45100.

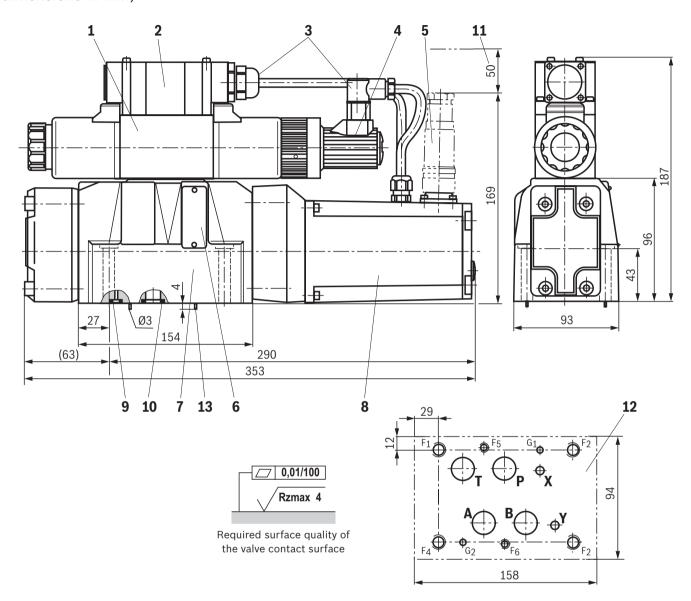


The dimensions are nominal dimensions which are subject to tolerances.

**Dimensions** for **electronics protection membrane "-967"** see page 25.

Valve mounting screws see page 26.

**Dimensions:** Size 16 (dimensions in mm)



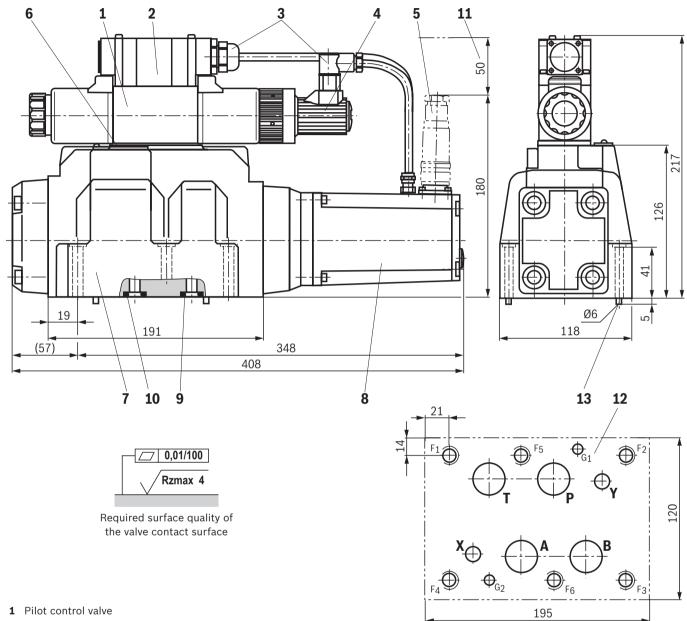
- 1 Pilot control valve
- 2 Electrical connection
- 3 Wiring and mating connector
- 4 Inductive position transducer (pilot control valve)
- 5 Mating connector 6-pole + PE (separate order, see page 28 and data sheet 08006)
- 6 Name plate
- 7 Main valve
- 8 Integrated electronics (OBE) and inductive position transducer (main valve)
- 9 Identical seal rings for ports X, Y
- 10 Identical seal rings for ports A, B, P, T
- 11 Space required for connection cable and to remove the mating connector
- Machined valve contact surface, porting pattern according to ISO 4401-07-07-0-05 (ports X, Y as required) Deviating from the standard: ports A, B, P, T – Ø20 mm
- 13 Locking pin

**Subplates** (separate order) with porting pattern according to ISO 4401-07-07-0-05 see data sheet 45100.

### Notice:

The dimensions are nominal dimensions which are subject to tolerances.

# **Dimensions:** Size 25 (dimensions in mm)



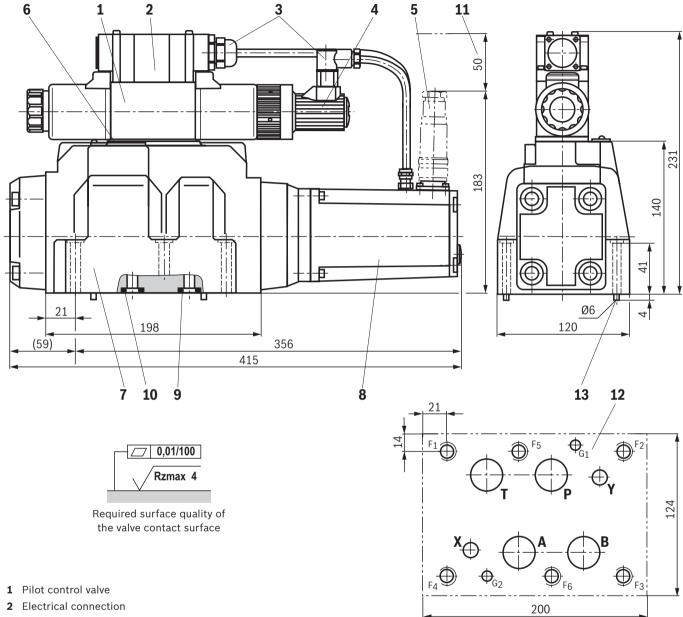
- 2 Electrical connection
- 3 Wiring and mating connector
- 4 Inductive position transducer (pilot control valve)
- Mating connector 6-pole + PE (separate order, see page 28 and data sheet 08006)
- 6 Name plate
- 7 Main valve
- 8 Integrated electronics (OBE) and inductive position transducer (main valve)
- 9 Identical seal rings for ports X, Y
- 10 Identical seal rings for ports A, B, P, T
- 11 Space required for connection cable and to remove the mating connector
- 12 Machined valve contact surface; porting pattern according to ISO 4401-08-08-0-05 (ports X, Y as required)
- 13 Locking pin

**Subplates** (separate order) with porting pattern according to ISO 4401-08-08-0-05 see data sheet 45100.

#### Motice:

The dimensions are nominal dimensions which are subject to tolerances.

# **Dimensions:** Size 27 (dimensions in mm)



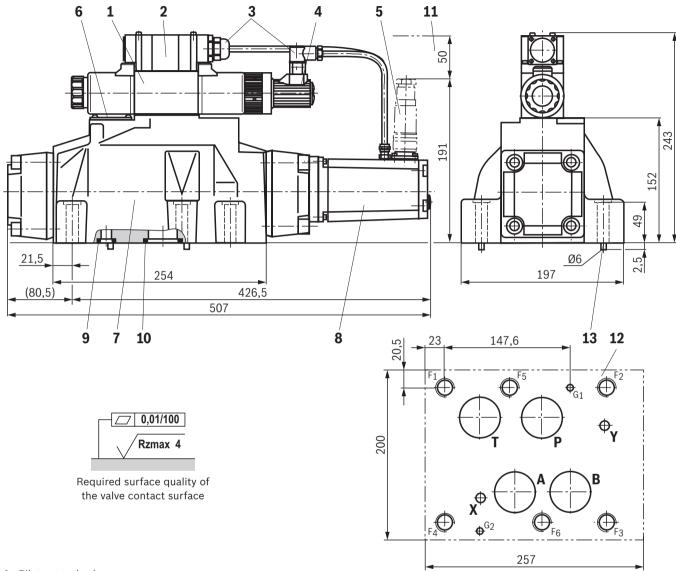
- 3 Wiring and mating connector
- 4 Inductive position transducer (pilot control valve)
- 5 Mating connector 6-pole + PE (separate order, see page 28 and data sheet 08006)
- 6 Name plate
- 7 Main valve
- 8 Integrated electronics (OBE) and inductive position transducer (main valve)
- 9 Identical seal rings for ports X, Y
- 10 Identical seal rings for ports A, B, P, T
- Space required for connection cable and to remove the mating connector
- Machined valve contact surface; porting pattern according to ISO 4401-08-08-0-05 (ports X, Y as required) Deviating from the standard: ports A, B, P, T − Ø32 mm
- 13 Locking pin

**Subplates** (separate order) with porting pattern according to ISO 4401-08-08-0-05 see data sheet 45100.

# Notice:

The dimensions are nominal dimensions which are subject to tolerances.

# **Dimensions:** Size 32 (dimensions in mm)



- 1 Pilot control valve
- 2 Electrical connection
- 3 Wiring and mating connector
- 4 Inductive position transducer (pilot control valve)
- Mating connector 6-pole + PE (separate order, see page 28 and data sheet 08006)
- 6 Name plate
- 7 Main valve
- 8 Integrated electronics (OBE) and inductive position transducer (main valve)
- 9 Identical seal rings for ports X, Y
- 10 Identical seal rings for ports A, B, P, T
- **11** Space required for connection cable and to remove the mating connector
- 12 Machined valve contact surface; porting pattern according to ISO 4401-10-09-0-05 (ports X, Y as required)

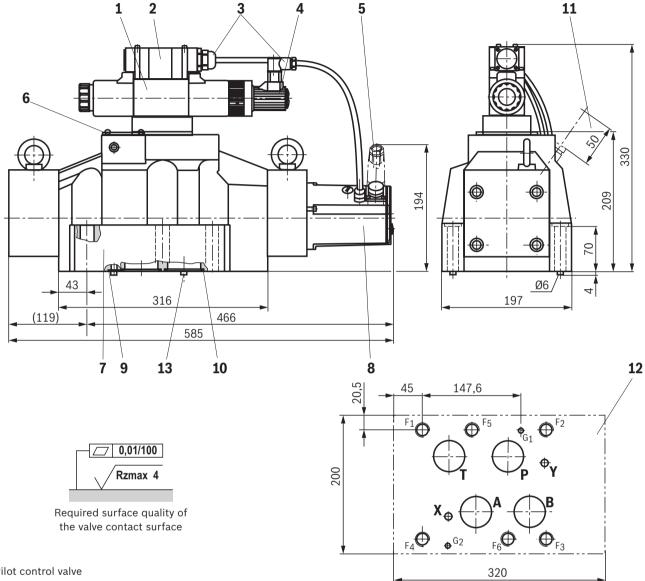
  Deviating from the standard:
  - ▶ Ports A, B, P, T Ø38 mm
  - ▶ Dimension G<sub>1</sub> according to DIN 24340 Form A
- 13 Locking pin

**Subplates** (separate order) with porting pattern according to ISO 4401-10-09-0-05 see data sheet 45100.



The dimensions are nominal dimensions which are subject to tolerances.

# Dimensions: Size 35 (dimensions in mm)



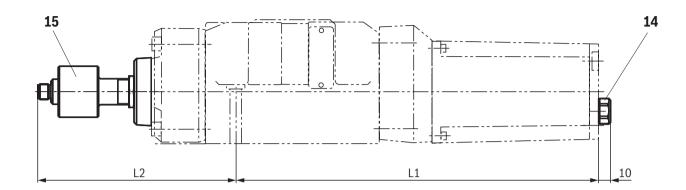
- 1 Pilot control valve
- 2 Electrical connection
- 3 Wiring and mating connector
- 4 Inductive position transducer (pilot control valve)
- Mating connector 6-pole + PE (separate order, see page 28 and data sheet 08006)
- Name plate
- 7 Main valve
- 8 Integrated electronics (OBE) and inductive position transducer (main valve)
- 9 Identical seal rings for ports X, Y
- 10 Identical seal rings for ports A, B, P, T
- 11 Space required for connection cable and to remove the mating connector
- 12 Machined valve contact surface; porting pattern according to ISO 4401-10-09-0-05 (ports X, Y as required) Deviating from the standard:
  - ► Ports A, B, P, T Ø50 mm
  - ▶ 1) Dimension G<sub>1</sub> according to DIN 24340 Form A
- 13 Locking pin

Subplates (separate order) with porting pattern according to ISO 4401-10-09-0-05 see data sheet 45100.



The dimensions are nominal dimensions which are subject to tolerances.

**Dimensions:** Spool position monitoring "M" and electronics protection membrane "-967" (dimensions in mm)



NG	L1	L2
10	240	_
16	286	151
25	347	143
27	353	144
32	422	168
35	463	201

- **14** Electronics protection membrane "-967"
- 15 Spool position monitoring "M", optional



The dimensions are nominal dimensions which are subject to tolerances.

# **Dimensions**

# Valve mounting screws (separate order)

Size	Quantity	Hexagon socket head cap screws	Material number			
10	4	ISO 4762 - M6 x 45 - 10.9-CM-Fe-ZnNi-5-Cn-T0-H-B tightening torque <i>M<sub>A</sub></i> = 13.5 Nm ±10%	R913043777			
	or					
	4	ISO 4762 - M6 x 45 - 10.9	Not included in the Rexroth			
		tightening torque $M_A$ = 15.5 Nm ±10%	delivery range			
16	2	ISO 4762 - M6 x 60 - 10.9-CM-Fe-ZnNi-5-Cn-T0-H-B tightening torque $M_A$ = 12.2 Nm ±10%	R913043410			
	4	ISO 4762 - M10 x 60 - 10.9-flZn/nc/480h/C	R913014770			
		tightening torque <b>M</b> <sub>A</sub> = 58 Nm ±20%				
	or 2	ISO 4762 - M6 x 60 - 10.9	Not included in the Rexroth			
	2	tightening torque $M_A$ = 15.5 Nm ±10%	delivery range			
	4	ISO 4762 - M10 x 60 - 10.9				
		tightening torque $M_A$ = 75 Nm ±20%				
25, 27	6	ISO 4762 - M12 x 60 - 10.9-flZn/nc/480h/C	R913015613			
		tightening torque M <sub>A</sub> = 100 Nm ±20%				
	or					
	6	ISO 4762 - M12 x 60	Not included in the Rexroth			
		tightening torque $M_A$ = 130 Nm ±20%	delivery range			
32	6	ISO 4762 - M20 x 80 - 10.9-flZn/nc/480h/C	R913008472			
		tightening torque <b>M</b> <sub>A</sub> = 340 Nm ±20%				
	or					
	6	ISO 4762 - M20 x 80 - 10.9	Not included in the Rexroth			
		tightening torque <b>M</b> <sub>A</sub> = 430 Nm ±20%	delivery range			
35	6	ISO 4762 - M20 x 100 - 10.9-flZn/nc/480h/C	R913015670			
		tightening torque <b>M</b> <sub>A</sub> = 465 Nm ±20%				
	or					
	6	ISO 4762 - M20 x 100 - 10.9	Not included in the Rexroth			
		tightening torque <b>M</b> <sub>A</sub> = 610 Nm ±20%	delivery range			

# Notice:

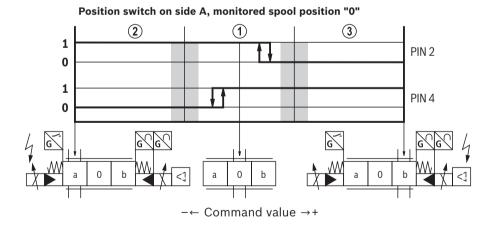
The tightening torque of the hexagon socket head cap screws refers to maximum operating pressure.

# Inductive position switch: Electrical connection

The electrical connection is realized via a 4-pole mating connector (separate order, see page 28) with connection thread M12 x 1.

Switching point	Within positive valve overlap		
Supply voltage	2032 V DC		
Admissible residual ripple	≤ 10%		
Current consumption	approx. 25 mA (no load)		
Outputs	2		
Output function	PNP		
Low level "0"	< 0.5 V DC		
High level "1"	<b>U</b> <sub>B</sub> −2 V DC		
Current carrying capacity	≤ 400 mA		
Signal delay time	≤ 15 ms (electrical, without switching time of valve)		
Reference potential	GND		
Pinout:	1 +24 V		
4 3	2 Switching output: 400 mA (valve opening P→A)		
70 <del>1</del> 01	<b>3</b> 0 V, GND		
1 2	4 Switching output: 400 mA (valve opening P→B)		

# Inductive position switch: Switching logics



- ① Central position (mechanical control spool overlap)
- ② Valve opening P→B
- 3 Valve opening P→A

Accessories: Mating connectors and cable sets (separate order)

# Valve with integrated electronics

Mating connectors 6-pole + PE	Design	Design	Material number	Data sheet
For the connection of valves with integrated	straight	Metal	R900223890	08006
electronics, round connector 6+PE, line cross-section	straight	Plastic	R900021267	08006
0.5 1.5 mm²	angled	Plastic	R900217845	_

Cable sets 6-pole + PE	Length in m	Material number	Data sheet
For the connection of valves with integrated	3.0	R901420483	08006
electronics, round connector 6+PE, straight connector, shielded, potted-in mating connector, line cross-section 0.75 mm <sup>2</sup>	5.0	R901420491	08006
	10.0	R901420496	08006
Closs-section 0.75 IIIIII	20.0	R901448068	-

### Sensors

Mating connectors 4-pole	Design	Line fitting	Material number	Data sheet
For the connection of sensors with connector "K24",	straight	PG7	R900773042	08006
"K35" and "K72", line cross-section 0.75 mm <sup>2</sup>	straight	PG9	R900031155	08006
	angled	PG7	R900779509	08006
	angled	PG9	R900082899	08006

Cable sets 4-pole	Design	Screening	Length in m	Material number	Data sheet
For the connection of sensors with connector "K24",	straight	yes	2.0	R900773031	08006
"K35" and "K72", line cross-section 0.34 mm <sup>2</sup>	straight	no	3.0	R900064381	08006
	straight	yes	5.0	R900779498	08006
	straight	no	10.0	R913005668	08006
	angled	yes	2.0	R900779504	08006
	angled	yes	5.0	R900779503	08006
	angled	no	10.0	R913011722	08006

# Project planning, installation and commissioning

- ► When designing safety-related controls, observe the applicable industry-specific standards and regulations.
- ▶ Due to the flexible use of valves in systems, the user has to check and ensure that the product properties comply with all functional and safety requirements of the overall system.
- ► Make sure that there are no switching shocks and that the valve control spool does not vibrate.
- ► Valves with spool position indicator may only be installed, adjusted, commissioned and maintained by specialists trained in hydraulics and electronics.
- ► Improper work at safety-related parts of controls may result in personal injury and damage to property.

# The following applies to all work carried out at the valve:

- Valves with spool position indicator must not be disassembled.
- ▶ The parts of the valves must not be exchanged.
- ▶ Integrated throttles must not be removed or modified.
- ► The spool position indicator may only be adjusted by the valve manufacturer.

#### **Further information**

► Subplates	Data sheet 45100
► Hydraulic fluids on mineral oil basis	Data sheet 90220
► Environmentally compatible hydraulic fluids	Data sheet 90221
► Flame-resistant, water-free hydraulic fluids	Data sheet 90222
► Flame-resistant hydraulic fluids - containing water (HFAE, HFAS, HFB, HFC)	Data sheet 90223
► Reliability characteristics according to EN ISO 13849	Data sheet 08012
► Hexagon socket head cap screw, metric/UNC	Data sheet 08936
► General product information on hydraulic products	Data sheet 07008
<ul><li>Installation, commissioning and maintenance of servo valves and high-response valves</li></ul>	Data sheet 07700
► Hydraulic valves for industrial applications	Data sheet 07600-B
<ul> <li>Assembly, commissioning and maintenance of hydraulic systems</li> </ul>	Data sheet 07900
► Selection of filters	www.boschrexroth.com/filter
► Information on available spare parts	www.boschrexroth.com/spc

# **Notes**

Bosch Rexroth AG Hydraulics Zum Eisengießer 1 97816 Lohr am Main, Germany Phone +49 (0) 93 52/18-0 documentation@boschrexroth.de www.boschrexroth.de © This document, as well as the data, specifications and other information set forth in it, are the exclusive property of Bosch Rexroth AG. It may not be reproduced or given to third parties without its consent.

The data specified above only serve to describe the product. No statements concerning a certain condition or suitability for a certain application can be derived from our information. The information given does not release the user from the obligation of own judgment and verification. It must be remembered that our products are subject to a natural process of wear and aging.

# Notes

Bosch Rexroth AG Hydraulics Zum Eisengießer 1 97816 Lohr am Main, Germany Phone +49 (0) 93 52/18-0 documentation@boschrexroth.de www.boschrexroth.de © This document, as well as the data, specifications and other information set forth in it, are the exclusive property of Bosch Rexroth AG. It may not be reproduced or given to third parties without its consent.

The data specified above only serve to describe the product. No statements concerning a certain condition or suitability for a certain application can be derived from our information. The information given does not release the user from the obligation of own judgment and verification. It must be remembered that our products are subject to a natural process of wear and aging.

# Notes

Bosch Rexroth AG Hydraulics Zum Eisengießer 1 97816 Lohr am Main, Germany Phone +49 (0) 93 52/18-0 documentation@boschrexroth.de www.boschrexroth.de © This document, as well as the data, specifications and other information set forth in it, are the exclusive property of Bosch Rexroth AG. It may not be reproduced or given to third parties without its consent. The data specified above only serve to describe the product. No statements concerning a certain condition or suitability for a certain application can be derived from our information. The information given does not release the user from the obligation of own judgment and verification. It must be remembered that our products are subject to a natural process of wear and aging.